

# Transfer Learning and CNN Applications

Feature Extraction • Fine-Tuning • Detection • Segmentation

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# The Problem

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## Training from scratch:

- ResNet-152 on ImageNet
- 2 weeks of training
- 8 GPUs
- 1.2 million labeled images

## Your reality:

- 500 labeled images
- 1 laptop (maybe a Colab GPU)
- Due Friday
- No budget for labeling

**How do we use deep learning with limited data and compute?**

# The Solution: Transfer Learning

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## Key Idea

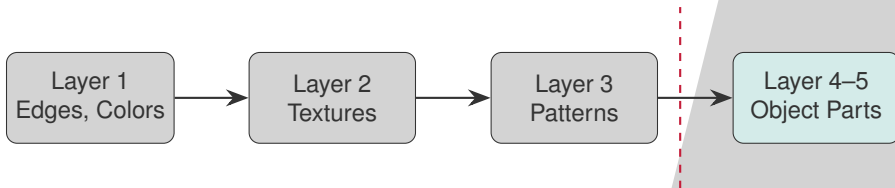
Use knowledge learned on a **large dataset** (ImageNet) to solve a **different task** with limited data.

### Two approaches:

1. **Feature Extraction** — freeze the pre-trained network, train a new head
2. **Fine-Tuning** — unfreeze some layers, adapt with a small learning rate

*Like a chef trained in French cuisine adapting to Italian — knife skills transfer, only the flavors change.*

# What CNN Layers Learn

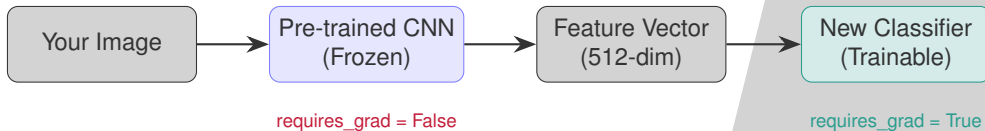


Generic (transfers everywhere)

Task-specific

Early layers detect universal features.  
Later layers specialize for the training task.

# Feature Extraction Strategy



- Load pre-trained model (e.g., ResNet-50)
- Freeze all layers — no gradient updates
- Replace final FC layer with your classifier
- Train only the new head (fast, needs little data)

# Feature Extraction in PyTorch

## Code Pattern

```
model = resnet50(weights='IMAGENET1K_V1')  
  
# Freeze all parameters  
for param in model.parameters():  
    param.requires_grad = False  
  
# Replace classifier head  
model.fc = nn.Linear(2048, num_classes)  
  
# Only optimize the new head  
optimizer = Adam(model.fc.parameters(), lr=0.001)
```

**Result:** Training only 0.1% of parameters, yet high accuracy.

# When Does Feature Extraction Work?

|                  |                  | Small Dataset         | Large Dataset              |
|------------------|------------------|-----------------------|----------------------------|
| Different Domain | Similar Domain   | Feature Extraction    | Fine-Tune All Layers       |
|                  | Different Domain | Fine-Tune Last Layers | Fine-Tune All (or Scratch) |

**Rule of thumb:** Start with feature extraction. Unfreeze more if needed.

# Quick Check

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## Question

**Q1:** You have 10,000 X-ray images and want to detect pneumonia. Starting with an ImageNet pre-trained model — feature extraction or fine-tuning?

**Q2:** Which layers of a pre-trained CNN are *most likely* to transfer across different image domains?

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## Question

**Q1:** You have 10,000 X-ray images and want to detect pneumonia. Starting with an ImageNet pre-trained model — feature extraction or fine-tuning?

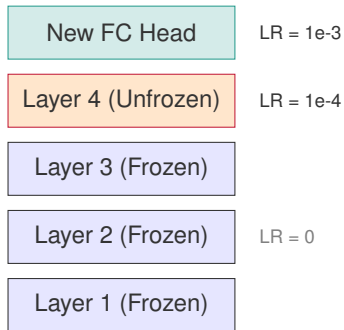
**Q2:** Which layers of a pre-trained CNN are *most likely* to transfer across different image domains?

**A1:** Fine-tune — different domain (medical), decent data size.

**A2:** Early layers (edges, textures) — they're universal.

# Fine-Tuning: The Idea

**Unfreeze** some pre-trained layers and train end-to-end with a **small learning rate**.



**Critical:** Use 10–100 $\times$  smaller LR for pre-trained layers. Otherwise you destroy useful features in the first epoch.

# Fine-Tuning Strategies

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1. **Conservative:** Unfreeze only the last 1–2 blocks
  - Safe for small datasets
  - Minimal risk of catastrophic forgetting
2. **Aggressive:** Unfreeze all layers with very small LR
  - Best for large datasets or very different domains
3. **Gradual Unfreezing:** Start head-only, unfreeze more each epoch
  - Safest for beginners
  - Less chance of catastrophic forgetting

**Always:** Train the new head first for 1–2 epochs before unfreezing.

# Practical Fine-Tuning Tips

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## Key Practices

- **Differential learning rates:** pre-trained layers get 10–100× smaller LR
- **Freeze batch norm:** keep BN in eval mode even while training
- **Train head first:** 1–2 epochs with backbone frozen, then unfreeze
- **Monitor val loss:** overfitting happens fast with small datasets
- **Use early stopping:** stop when val loss plateaus or increases

*“When in doubt, start frozen. Unfreeze only if accuracy plateaus.”*

Coming Up Next

**Part 2:** Domain Adaptation, Object Detection, and Image Segmentation

# The Domain Shift Problem

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## The Problem

Model trained on domain A, deployed on domain B → **performance drops.**

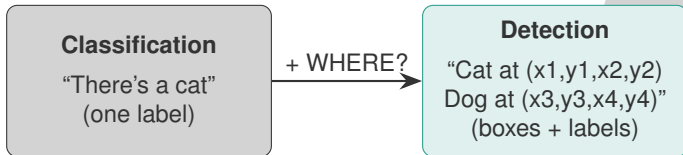
### Examples:

- Studio photos → phone camera photos
- US hospital X-rays → rural clinic X-rays
- Synthetic training data → real-world deployment

**Simplest fix:** Fine-tune on a small labeled set from the target domain.  
Even 100–500 target samples can significantly close the gap.

# From Classification to Detection

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**Detection answers two questions:** WHAT is in the image and WHERE is it?

Use cases: self-driving cars, security cameras, medical imaging, retail analytics

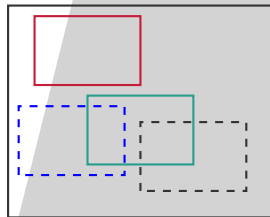
# The Naive Approach: Sliding Window

**Idea:** Slide a window across the image at every position and scale. Classify each crop.

**Problem:**

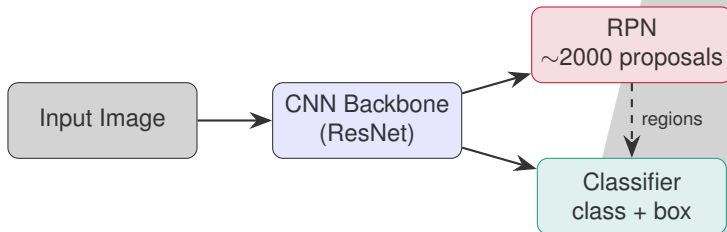
- $1000 \times 1000$  image
- 100 different scales
- Stride of 10 pixels
- = Millions of forward passes

*Way too slow for real-world use.*



Many overlapping windows

# Faster R-CNN: Two-Stage Detection



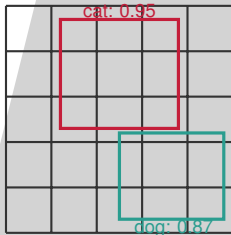
- **Stage 1:** Region Proposal Network (RPN) proposes “interesting” regions
- **Stage 2:** Classify each region + refine the bounding box
- Backbone features are **shared** — compute once, reuse many times

# YOLO: You Only Look Once

## Single-Shot Detection

- Divide image into  $S \times S$  grid
- Each cell predicts:
  - $B$  bounding boxes + confidence
  - $C$  class probabilities
- **One forward pass** for everything
- Real-time capable (30+ FPS)

**Trade-off:** Faster but slightly less accurate on small objects.



# Detection: Two Families

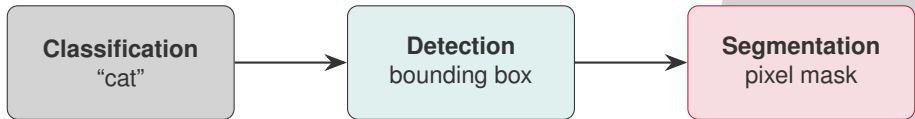
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|               | Two-Stage (R-CNN)    | Single-Shot (YOLO) |
|---------------|----------------------|--------------------|
| Speed         | Slower               | <b>Real-time</b>   |
| Accuracy      | <b>Higher</b>        | Slightly lower     |
| Small objects | <b>Better</b>        | Weaker             |
| Use case      | Medical, high-stakes | Video, robotics    |

Both use **pre-trained CNN backbones** — transfer learning is the foundation!

*In practice, YOLO dominates industry because speed usually matters more than the last 1% accuracy.*

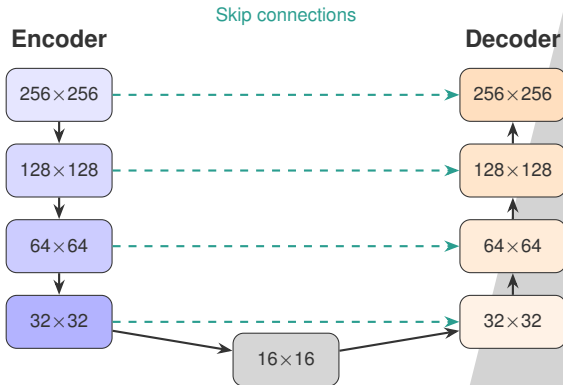
# Beyond Boxes: Pixel-Level Predictions



- **Semantic segmentation:** classify every pixel (all cats = one color)
- **Instance segmentation:** distinguish individuals (cat 1 vs. cat 2)

Why? Medical imaging needs **exact boundaries**, not rectangles.

# U-Net: Encoder-Decoder with Skip Connections



- **Encoder:** downsamples, builds semantic features
- **Decoder:** upsamples back to full resolution
- **Skip connections:** preserve fine spatial details lost during downsampling

# Segmentation Applications

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## Medical

Tumor boundaries  
Cell segmentation  
Organ delineation

## Autonomous Driving

Road vs. sidewalk  
Cars vs. pedestrians  
Lane detection

## Satellite

Land use mapping  
Crop classification  
Deforestation tracking

All use the same principle: **encoder-decoder + skip connections + pre-trained backbone.**

# Quick Check

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## Question

**Q1:** YOLO vs. Faster R-CNN — which would you pick for processing 30fps dashcam video in a self-driving car?

**Q2:** What do skip connections in U-Net help preserve that downsampling destroys?

# Quick Check

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## Question

**Q1:** YOLO vs. Faster R-CNN — which would you pick for processing 30fps dashcam video in a self-driving car?

**Q2:** What do skip connections in U-Net help preserve that downsampling destroys?

**A1:** YOLO — real-time speed is critical at 30fps.

**A2:** Fine spatial details — edges, boundaries, exact object outlines.

# Practical Tips for Training CNNs

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## Rules of Thumb

1. **Always start pre-trained** — training from scratch is a last resort
2. **Data augmentation** — flips, crops, color jitter, rotation (free extra data)
3. **LR schedule** — warmup + cosine decay or step decay
4. **Progressive resizing** — train  $128 \times 128$  first, then  $224 \times 224$
5. **Monitor both losses** — if train  $\downarrow$  but val  $\uparrow$ , stop immediately

# Architecture Cheat Sheet

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| Task                   | Default Choice | Alternative      |
|------------------------|----------------|------------------|
| Classification         | ResNet-50      | EfficientNet     |
| Detection (speed)      | YOLOv8         | SSD              |
| Detection (accuracy)   | Faster R-CNN   | DETR             |
| Segmentation (medical) | U-Net          | —                |
| Segmentation (general) | DeepLabV3      | Segment Anything |

**When in doubt:** ResNet-50 backbone + transfer learning.  
It's “boring” but it works.

# Recap: Three Big Ideas

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## 1. **Transfer Learning** — don't train from scratch

- Feature extraction (freeze) vs. fine-tuning (unfreeze)
- Decision depends on data size  $\times$  domain similarity

## 2. **Object Detection** — WHAT + WHERE

- Faster R-CNN (accurate, two-stage) vs. YOLO (fast, single-shot)

## 3. **Image Segmentation** — pixel-level understanding

- Encoder-decoder + skip connections (U-Net)

**Next session:** What happens when your data has a *time* dimension? → **RNNs**



# Thank You!

Questions?

**Priyansh Saxena**

All lecture materials available at:

[www.priyanshsaxena.com/sst-deep-learning-nn](http://www.priyanshsaxena.com/sst-deep-learning-nn)